

Claims

What is claimed is:

1. A haptic for an ophthalmological implant comprising:
 - a) an arcuate haptic;
 - b) at least two spaced apart eyelets on said haptic adapted for receiving a securing member, and attaching onto said securing member.
2. A ophthalmological suture guide device comprising:
 - a) a base portion having a leading end having a blunted tip adapted for insertion into an eye, at least two channels, defined in said base portion and extending through at least said leading end for receiving an end of a suture, a needle or a combination thereof; and
 - b) the spacing between said channels of said leading end approximating the spacing between suture insertions into an ophthalmological body.
3. A method for implanting a haptic into an eye comprising the steps of:
 - a) providing an implant having at least one arcuate haptic, said haptic including at least two spaced apart eyelets adapted for receiving a securing member and attaching onto said securing member;
 - b) inserting a securing member into an eye; and
 - c) attaching said haptic to said securing member.
4. The haptic of claim 1 further comprising an optic secured to said haptic.
5. The haptic of claim 4 further comprising a second haptic having two spaced apart eyelets.

6. The haptic of claim 4 wherein said eyelets depend inwardly toward said optic relative to said haptic.

7. The haptic of claim 1 wherein said haptic is arcuate.

8. The haptic of claim 1 wherein each of said eyelets includes an aperture defined by an arm that depends from said haptic and folds over upon itself.

9. The haptic of claim 8 wherein a notch is defined at said arm for guiding a securing member into said eyelet.

10. A suture guide according to claim 2 wherein said base portion substantially entirely encloses said channels along the entire length of said channels.

11. A suture guide according to claim 2 wherein said base portion includes a longitudinal portion that is open.

12. A suture guide according to claim 2 wherein said channels terminate adjacent the leading end of said gripping portion and are spaced from each other at such point at about 1 to about 2.5 mm.

13. A suture guide according to claim 2 wherein said channels are defined in spaced apart finger protrusions associated with said gripping portion.

14. A suture guide according to claim 2 further comprising a member attached to said gripping portion to retrieval of said guide from a patient.

15. A method according to claim 3 wherein said implant is an intraocular lens.

16. A method according to claim 3 wherein said securing member is a suture.

17. A method according to claim 16 wherein said inserting step employs a suture guide device having at least two channels defined therein for guiding a suture through each channel and into an eye.

18. A method according to claim 16 wherein said suture is passed through a sclera of an eye.

19. A method according to claim 18 wherein upon said attaching step the haptic is secured to the eye by four point fixation.

20. A method according to claim 3 further comprising a second haptic that is secured to the eye by a suture.